

HT2015: SC4

Statistical Data Mining and Machine Learning

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<http://www.stats.ox.ac.uk/~sejdinov/sdmml.html>

Parametric vs Nonparametric models

- **Parametric models** have a fixed finite number of parameters, regardless of the dataset size. In the Bayesian setting, given the parameter vector θ , the predictions are independent of the data \mathcal{D} .

$$p(\tilde{x}, \theta | \mathcal{D}) = p(\theta | \mathcal{D})p(\tilde{x} | \theta)$$

Parameters can be thought of as a data summary: communication channel flows from data to the predictions through the parameters.
Model-based learning (e.g., mixture of K multivariate normals)

- **Nonparametric models** allow the number of “parameters” to grow with the dataset size. Alternatively, predictions depend on the data (and the hyperparameters).
Memory-based learning (e.g., kernel density estimation)

Dirichlet Process

- We have seen that a conjugate prior over a probability mass function (π_1, \dots, π_K) is a Dirichlet distribution $\text{Dir}(\alpha_1, \dots, \alpha_K)$. Can we create a **prior over probability distributions** on \mathbb{R} ?
- **Dirichlet process** $\text{DP}(\alpha, h)$, $\alpha > 0$ and H a probability distribution on \mathbb{R}
A random probability distribution F is said to follow a Dirichlet process if when restricted to any finite partition it has a Dirichlet distribution, i.e., for any partition A_1, \dots, A_K of \mathbb{R} ,
 $(F(A_1), \dots, F(A_K)) \sim \text{Dir}(\alpha h(A_1), \dots, \alpha h(A_K))$



- **Stick-breaking construction** allows us to draw from a Dirichlet process:

- 1 Draw $s_1, s_2, \dots \stackrel{i.i.d.}{\sim} h$
- 2 Draw $v_1, v_2, \dots \stackrel{i.i.d.}{\sim} \text{Beta}(1, \alpha)$
- 3 Set $w_1 = v_1, w_2 = v_2(1 - v_1), \dots, w_j = v_j \prod_{\ell=1}^{j-1} (1 - v_\ell) \dots$

Then $\sum_{\ell=1}^{\infty} w_\ell \delta_{s_\ell} \sim \text{DP}(\alpha, h)$

Dirichlet Process and a Posterior over Distributions

- Given data $\mathcal{D} = \{x_i\}_{i=1}^n \stackrel{i.i.d.}{\sim} F$, $x_i \in \mathbb{R}^p$, we put a prior $\text{DP}(\alpha, h)$ on F
- Posterior $p(F | \mathcal{D})$ is $\text{DP}(\alpha + n, \bar{h})$, where $\bar{h} = \frac{n}{n+\alpha} \hat{F} + \frac{\alpha}{n+\alpha} h$ and $\hat{F} = \frac{1}{n} \sum_{i=1}^n \delta_{x_i}$ is the empirical distribution.
- But how to reason about this posterior? Answer: sample from it!

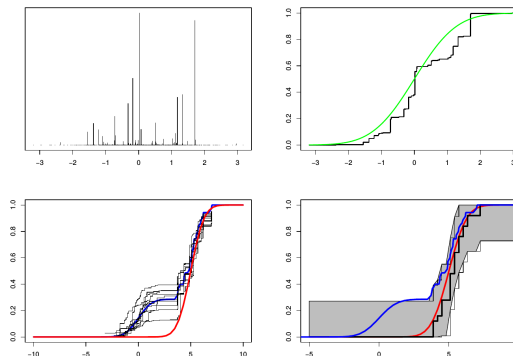


Figure : top left: a draw from $\text{DP}(10, \mathcal{N}(0, 1))$; top right: resulting cdf; bottom left: draws from a posterior based on $n = 25$ observations from a $\mathcal{N}(5, 1)$ distribution (red); bottom right: Bayesian posterior mean (blue), empirical cdf (black).

Dirichlet Process Mixture Models

- In mixture models for clustering, we had to pick the number of clusters K . Can we automatically infer K from data?
- Just use an infinite mixture model

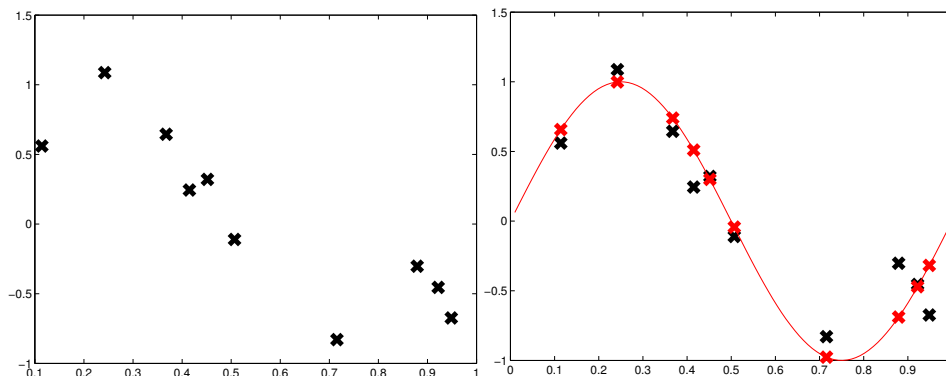
$$g(x) = \sum_{k=1}^{\infty} \pi_k p(x|\theta_k)$$

The following generative process defines an implicit prior on g :

- ① Draw $F \sim \text{DP}(\alpha, h)$
 - ② Draw $\theta_1, \dots, \theta_n | F \stackrel{i.i.d.}{\sim} F$
 - ③ Draw $x_i | \theta_i \sim p(\cdot | \theta_i)$
- F is discrete and will get ties - ties form clusters.
 - Posterior distribution is more involved but can be sampled from¹.

¹Radford Neal, 2000: Markov Chain Sampling Methods for Dirichlet Process Mixture Models

Regression



- We are given a dataset $\mathcal{D} = \{(x_i, y_i)\}_{i=1}^n$, $x_i \in \mathbb{R}^p$, $y_i \in \mathbb{R}$.
- Regression: learn the underlying real-valued function $f(x)$.

Gaussian Processes

Different Flavours of Regression

- We can model response y_i as a noisy version of the underlying function f evaluated at input x_i :

$$y_i | f, x_i \sim \mathcal{N}(f(x_i), \sigma^2)$$

Appropriate loss: $L(y, f(x)) = (y - f(x))^2$

- **Frequentist Parametric** approach: model f as f_θ for some parameter vector θ . Fit θ by ML / ERM with squared loss (**linear regression**).
- **Frequentist Nonparametric** approach: model f as the unknown parameter taking values in an infinite-dimensional space of functions. Fit f by **regularized** ML / ERM with squared loss (**kernel ridge regression**).
- **Bayesian Parametric** approach: model f as f_θ for some parameter vector θ . Put a prior on θ and compute a posterior $p(\theta | \mathcal{D})$ (**Bayesian linear regression**).
- **Bayesian Nonparametric** approach: treat f as the random variable taking values in an infinite-dimensional space of functions. Put a prior over functions $f \in \mathcal{F}$, and compute a posterior $p(f | \mathcal{D})$ (**Gaussian Process regression**).

- Just work with the function values at the inputs $\mathbf{f} = (f(x_1), \dots, f(x_n))^T$
- What properties of the function can we incorporate?

- Multivariate normal prior on \mathbf{f} :

$$\mathbf{f} \sim \mathcal{N}(0, \mathbf{K})$$

- Use a kernel function k to define \mathbf{K} :

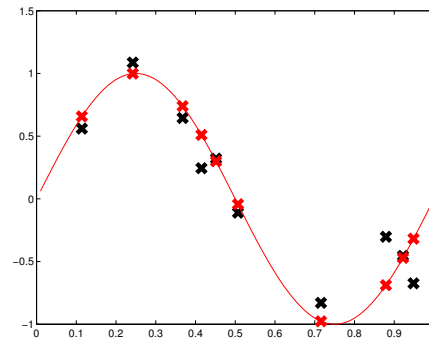
$$\mathbf{K}_{ij} = k(x_i, x_j)$$

- Expect regression functions to be smooth: If x and x' are close by, then $f(x)$ and $f(x')$ have similar values, i.e. strongly correlated.

$$\begin{pmatrix} f(x) \\ f(x') \end{pmatrix} \sim \mathcal{N} \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} k(x, x) & k(x, x') \\ k(x', x) & k(x', x') \end{pmatrix} \right)$$

In particular, want $k(x, x') \approx k(x, x) = k(x', x')$.

The prior $p(\mathbf{f})$ encodes our prior knowledge about the function.



- Model:

$$\mathbf{f} \sim \mathcal{N}(0, \mathbf{K})$$

$$y_i | f_i \sim \mathcal{N}(f_i, \sigma^2)$$

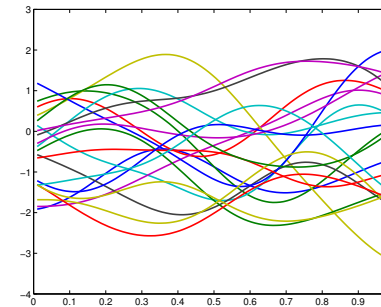
Gaussian Processes

- What does a multivariate normal prior mean?
- Imagine \mathbf{x} forms an infinitesimally dense grid of data space. Simulate prior draws

$$\mathbf{f} \sim \mathcal{N}(0, \mathbf{K})$$

Plot f_i vs x_i for $i = 1, \dots, n$.

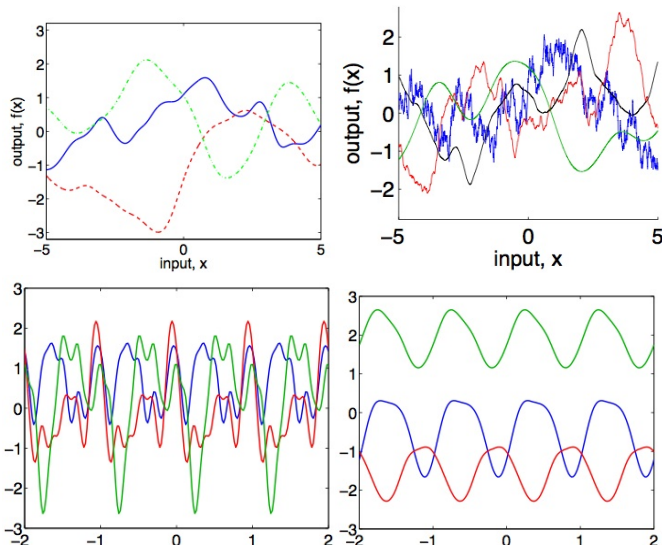
- The corresponding prior over functions is called a **Gaussian Process** (GP): any finite number of evaluations of which follow a Gaussian distribution.



<http://www.gaussianprocess.org/>

Gaussian Processes

- Different kernels lead to different function characteristics.



Carl Rasmussen. Tutorial on Gaussian Processes at NIPS 2006.

Gaussian Processes

$$\mathbf{f} | \mathbf{x} \sim \mathcal{N}(0, \mathbf{K})$$

$$\mathbf{y} | \mathbf{f} \sim \mathcal{N}(\mathbf{f}, \sigma^2 I)$$

- Posterior distribution:

$$\mathbf{f} | \mathbf{y} \sim \mathcal{N}(\mathbf{K}(\mathbf{K} + \sigma^2 I)^{-1} \mathbf{y}, \mathbf{K} - \mathbf{K}(\mathbf{K} + \sigma^2 I)^{-1} \mathbf{K})$$

- Posterior predictive distribution: Suppose \mathbf{x}' is a test set. We can extend our model to include the function values \mathbf{f}' at the test set:

$$\begin{pmatrix} \mathbf{f} \\ \mathbf{f}' \end{pmatrix} | \mathbf{x}, \mathbf{x}' \sim \mathcal{N} \left(\begin{pmatrix} 0 \\ 0 \end{pmatrix}, \begin{pmatrix} \mathbf{K}_{\mathbf{x}\mathbf{x}} & \mathbf{K}_{\mathbf{x}\mathbf{x}'} \\ \mathbf{K}_{\mathbf{x}'\mathbf{x}} & \mathbf{K}_{\mathbf{x}'\mathbf{x}'} \end{pmatrix} \right)$$

$$\mathbf{y} | \mathbf{f} \sim \mathcal{N}(\mathbf{f}, \sigma^2 I)$$

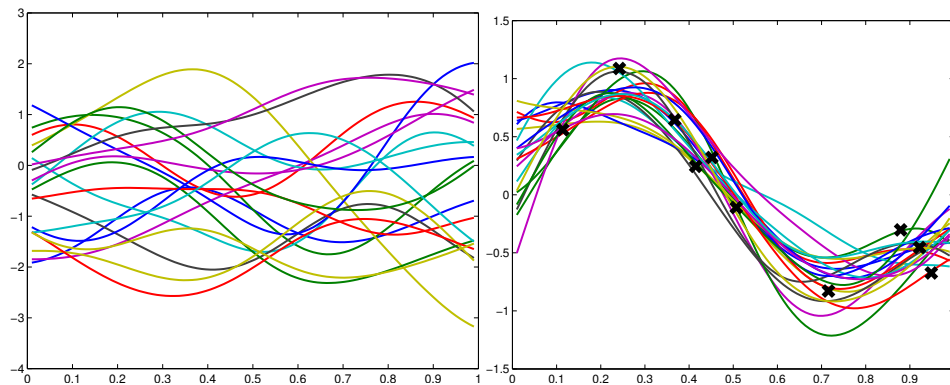
where $\mathbf{K}_{\mathbf{x}\mathbf{x}'}$ is matrix with (i, j) -th entry $k(x_i, x'_j)$.

- Some manipulation of multivariate normals gives:

$$\mathbf{f}' | \mathbf{y} \sim \mathcal{N}(\mathbf{K}_{\mathbf{x}'\mathbf{x}}(\mathbf{K}_{\mathbf{x}\mathbf{x}} + \sigma^2 I)^{-1} \mathbf{y}, \mathbf{K}_{\mathbf{x}'\mathbf{x}'} - \mathbf{K}_{\mathbf{x}'\mathbf{x}}(\mathbf{K}_{\mathbf{x}\mathbf{x}} + \sigma^2 I)^{-1} \mathbf{K}_{\mathbf{x}\mathbf{x}'})$$

Gaussian Processes

GP regression demo



<http://www.tmpl.fi/gp/>

Summary

- A whirlwind journey through data mining and machine learning techniques:
 - **Unsupervised learning:** PCA, MDS, Isomap, Hierarchical clustering, K-means, mixture modelling, EM algorithm, Dirichlet process mixtures.
 - **Supervised learning:** LDA, QDA, naïve Bayes, logistic regression, SVMs, kernel methods, kNN, deep neural networks, Gaussian processes, decision trees, ensemble methods: random forests, bagging, stacking, dropout and boosting.
 - **Conceptual frameworks:** prediction, performance evaluation, generalization, overfitting, regularization, model complexity, validation and cross-validation, bias-variance tradeoff.
 - **Theory:** decision theory, statistical learning theory, convex optimization, Bayesian vs. frequentist learning, parametric vs non-parametric learning.
- **Further resources:**
 - Machine Learning Summer Schools, videolectures.net.
 - Conferences: NIPS, ICML, UAI, AISTATS.
 - Mailing list: ml-news.

Thank You!