SC4/SM4 Data Mining and Machine Learning Dimensionality Reduction

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Slides and other materials available at:

<http://www.stats.ox.ac.uk/~sejdinov/dmml>

Course Structure

• MMath Part C & MSc in Applied Statistics

Lectures:

- Tuesdays 14:00-15:00, LG.01.
- **Thursdays 12:00-13:00, LG.01.**

MSc:

- 4 problem sheets, discussed at the classes: Mondays 11:00-12:00 (weeks 3,5,7,8), LG.01.
- Practicals: Fridays 14:00-16:00 (weeks 5 and **8 group assessed**), LG.02.

Part C:

- 4 problem sheets, **solutions due Mondays 10:00 in weeks 3,5,7,8**.
- Class Tutors: [Jovana Mitrovic](mailto:jovana.mitrovic@spc.ox.ac.uk) and [Leonard Hasenclever.](mailto:leonard.hasenclever@spc.ox.ac.uk)
- **Teaching Assistants: [Leon Law](mailto:ho.law@spc.ox.ac.uk) and [Fadhel Ayed.](mailto:fadhel.ayed@some.ox.ac.uk)**
- Classes (Group I): Wednesdays 14:30-16:00 (weeks 3,5,7,8), LG.04.
- Classes (Group II): Wednesdays 17:00-18:30 (weeks 3,5,7,8), LG.04.
- Classes (Group III): Fridays 16:30-18:00 (weeks 3,5,7,8), LG.04.
- Please **sign up for the classes today** on the sign up sheet!

Course Aims

- ¹ Have ability to identify and use appropriate methods and models for given data and task.
- ² Have ability to use the relevant software packages to analyse data, interpret results, and evaluate methods.
- ³ Understand the statistical theory framing machine learning and data mining.
- ⁴ Able to construct appropriate models and derive learning algorithms for given data and task.

What is Data Mining?

Oxford Dictionary

The practice of examining large pre-existing databases in order to **generate new information**.

Encyclopaedia Britannica

Also called **knowledge discovery** in databases, in computer science, the process of discovering **interesting and useful patterns and relationships** in large volumes of data.

What is Machine Learning?

Arthur Samuel, 1959

Field of study that gives computers the ability to **learn** without being explicitly programmed.

Tom Mitchell, 1997

Any computer program that **improves its performance** at some task **through experience**.

Kevin Murphy, 2012

To develop methods that can **automatically** detect **patterns in data**, and then to use the uncovered patterns to **predict** future data or other outcomes of interest.

What is Machine Learning?

[recommender systems](http://link.springer.com/article/10.1007%2Fs00144-010-0005-2)

[image](http://bits.blogs.nytimes.com/2014/08/18/computer-eyesight-gets-a-lot-more-accurate) [recognition](http://www.cs.toronto.edu/~fritz/absps/imagenet.pdf)

[machine translation](https://research.googleblog.com/2016/09/a-neural-network-for-machine.html) [self-driving cars](http://spectrum.ieee.org/cars-that-think/transportation/advanced-cars/deep-learning-makes-driverless-cars-better-at-spotting-pedestrians)

[DQN Atari games](https://www.youtube.com/watch?v=mArrNRWQEso&t=2m35s)

[AlphaGo](https://blog.google/topics/machine-learning/alphago-machine-learning-game-go/)

Types of Machine Learning

Supervised learning

- **•** Data contains "labels": every example is an input-output pair
- classification, regression
- Goal: **prediction on new examples**

Unsupervised learning

- Extract key features of the "unlabelled" data
- clustering, signal separation, density estimation
- Goal: **representation, hypothesis generation, visualization**

Types of Machine Learning

Semi-supervised Learning

A database of examples, only a small subset of which are labelled.

Multi-task Learning

A database of examples, each of which has multiple labels corresponding to different prediction tasks.

Reinforcement Learning

An agent acting in an environment, given rewards for performing appropriate actions, learns to maximize their reward.

Software

R

- Python: [scikit-learn,](http://scikit-learn.org/stable/) [mlpy,](http://mlpy.sourceforge.net/) [Theano](http://deeplearning.net/software/theano/)
- [Weka,](http://www.cs.waikato.ac.nz/ml/weka/) [mlpack,](http://mlpack.org/) [Torch,](http://torch.ch/) [Shogun,](http://www.shogun-toolbox.org/) [TensorFlow.](https://www.tensorflow.org/)..
- Matlab/Octave

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- **Doctoral Training in Next Generational Statistical Science: theory,** methods and applications of Statistical Science for 21st Century data-intensive environments and large-scale models.
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- [Website for prospective students.](http://www.oxwasp-cdt.ac.uk/how-to-apply.html)
- **Deadline: January 20, 2017**

Unsupervised Learning: Dimensionality Reduction

Unsupervised Learning

Goals:

- Find the variables that summarise the data / capture relevant information.
- **•** Discover informative ways to visualise the data.
- Discover the subgroups among the observations.
- It is often much easier to obtain unlabeled data than labeled data!

Exploratory Data Analysis

Notation

- Data consists of *p* variables (features/attributes/dimensions) on *n* examples (items/observations).
- \bullet $X = (x_{ij})$ is a $n \times p$ -matrix with $x_{ij} :=$ the *j*-th variable for the *i*-th example

- Denote the *i*-th data item by $x_i \in \mathbb{R}^p$ (we will treat it as a column vector: it is the transpose of the *i*-th row of X).
- Assume x_1, \ldots, x_n are **independently and identically distributed** samples of a **random vector** X over \mathbb{R}^p . The *j*-th dimension of X will be denoted $X^{(j)}$.

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Crabs Data ($n = 200, p = 5$)

Campbell (1974) studied rock crabs of the genus **leptograpsus**. One species, **L. variegatus**, had been split into two new species according to their colour: orange and blue. Preserved specimens lose their colour, so it was hoped that morphological differences would enable museum material to be classified.

Data are available on 50 specimens of each sex of each species. Each specimen has measurements on:

- \bullet the width of the frontal lobe FL .
- \bullet the rear width RW.
- \bullet the length along the carapace midline CL ,
- \bullet the maximum width cw of the carapace, and
- \bullet the body depth BD in mm.

in addition to colour/species and sex (we will later view these as labels, but will ignore for now).

Crabs Data

```
## load package MASS containing the data
library(MASS)
```

```
## extract variables we will look at
varnames<-c('FL','RW','CL','CW','BD')
Crabs <- crabs[,varnames]
```

```
## look at raw data
Crabs
```
Crabs Data

look at raw data Crabs

Univariate Boxplots

boxplot(Crabs)

Univariate Histograms

Frequency

Histogram of Crabs\$FL Histogram of Crabs\$RW Histogram of Crabs\$CL S 10 20 30 40 50 \overline{a} 10 20 30 40 8 10 30 50 g R Frequency Frequency $\rm s$ \approx g 20 $\tilde{ }$ \Rightarrow \supseteq \overline{a} \overline{a} 10 15 20 10 15 20 10 20 30 40 50 FL: Frontal Lobe Size (mm) RW: Rear Width (mm) CL: Carapace Length (mm)

Histogram of Crabs\$CW

Histogram of Crabs\$BD

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Simple Pairwise Scatterplots

pairs(Crabs)

Visualisation and Dimensionality Reduction

The summary plots are useful, but limited use if the dimensionality *p* is high (a few dozens or even thousands).

- Constrained to view data in 2 or 3 dimensions
- Approach: look for 'interesting' projections of X into lower dimensions
- Hope that even though *p* is large, considering only carefully selected $k \ll p$ dimensions is just as informative.

Dimensionality reduction

For each data item $x_i \in \mathbb{R}^p$, find its lower dimensional representation $z_i \in \mathbb{R}^k$ with $k \ll p$.

• Map $x \mapsto z$ should preserve the **interesting statistical properties** in data.

Dimensionality reduction

- deceptively many variables to measure, many of them redundant / correlated to each other (large *p*)
- \bullet often, there is a simple but unknown underlying relationship hiding
- **•** example: ball on a frictionless spring recorded by three different cameras
	- our imperfect measurements obfuscate the true underlying dynamics
	- are our coordinates meaningful or do they simply reflect the method of data gathering?

J. Shlens, [A Tutorial on Principal Component Analysis,](http://arxiv.org/abs/1404.1100) 2005

Principal Components Analysis (PCA)

- PCA considers interesting directions to be those with greatest **variance**.
- A **linear** dimensionality reduction technique: looks for a **new basis** to represent a noisy dataset.
- Workhorse for many different types of data analysis (often used for data preprocessing before supervised techniques are applied).
- Often the first thing to run on high-dimensional data.

Principal Components Analysis (PCA)

• Assume that the dataset is centred, i.e.,

$$
\bar{x} = \frac{1}{n} \sum_{i=1}^n x_i = 0.
$$

• Sample covariance:

$$
S = \frac{1}{n-1} \sum_{i=1}^{n} (x_i - \bar{x})(x_i - \bar{x})^{\top}
$$

=
$$
\frac{1}{n-1} \sum_{i=1}^{n} x_i x_i^{\top} = \frac{1}{n-1} \mathbf{X}^{\top} \mathbf{X}.
$$

PCA

PCA recovers an orthonormal basis v_1, v_2, \ldots, v_p in \mathbb{R}^p – vectors v_i are **called principal components (PC) or loading vectors** – such that:

- The first principal component (PC) v_1 is the **direction of greatest variance** of data.
- The *j*-th PC *v^j* is the **direction orthogonal to** *v*1, *v*2, . . . , *vj*−¹ **of greatest variance**, for $j = 2, \ldots, p$.

Principal Components Analysis (PCA)

The *k*-dimensional representation of data item *xⁱ* is the vector of projections of *xⁱ* onto first *k* PCs:

$$
z_i = V_{1:k}^{\top} x_i = \left[v_1^{\top} x_i, \dots, v_k^{\top} x_i \right]^{\top} \in \mathbb{R}^k,
$$

where $V_{1:k} = [v_1, \ldots, v_k]$.

Transformed data matrix, also called the **scores matrix**

 $\mathbf{Z} = \mathbf{X} V_{1:k} \in \mathbb{R}^{n \times k}$.

Reconstruction of x_i

$$
\hat{x}_i = V_{1:k} V_{1:k}^\top x_i.
$$

PCA gives the **optimal linear reconstruction** of the original data based on a *k*-dimensional compression (problem sheets).

Deriving the First Principal Component

- Our data set is an *i.i.d.* sample ${x_i}_{i=1}^n$ of a random vector $X = [X^{(1)} \dots X^{(p)}]^\top.$
- For the 1 *st* PC, we seek a derived scalar variable of the form

$$
Z^{(1)} = v_1^{\top} X = v_{11} X^{(1)} + v_{12} X^{(2)} + \dots + v_{1p} X^{(p)}
$$

where $v_1 = [v_{11}, \ldots, v_{1p}]^\top \in \mathbb{R}^p$ are chosen to maximise the sample variance

$$
\widehat{\text{Var}}(Z^{(1)}) = v_1^{\top} \widehat{\text{Cov}}(X) v_1 = v_1^{\top} S v_1.
$$

• Optimisation problem

$$
\begin{aligned}\n&\max_{\mathbf{v}_1} \mathbf{v}_1^\top S \mathbf{v}_1\\ \n&\text{subject to: } \mathbf{v}_1^\top \mathbf{v}_1 = 1.\n\end{aligned}
$$

Deriving the First Principal Component

• Lagrangian of the problem is given by:

$$
\mathcal{L}(\mathbf{v}_1, \lambda_1) = \mathbf{v}_1^\top S \mathbf{v}_1 - \lambda_1 (\mathbf{v}_1^\top \mathbf{v}_1 - 1).
$$

• The corresponding vector of partial derivatives is

$$
\frac{\partial \mathcal{L}(v_1, \lambda_1)}{\partial v_1} = 2Sv_1 - 2\lambda_1v_1.
$$

- Setting this to zero reveals the eigenvector equation $Sv_1 = \lambda_1 v_1$, i.e. v_1 must be an eigenvector of *S* and the dual variable λ_1 is the corresponding eigenvalue.
- Since $v_1^\top S v_1 = \lambda_1 v_1^\top v_1 = \lambda_1$, the first PC must be the eigenvector associated with the largest eigenvalue of *S*.

PCA as eigendecomposition of the covariance matrix

- The 2 *nd* PC is chosen to be orthogonal with the 1 *st* and is computed in a similar way (see notes). It will have the largest variance in the remaining *p* − 1 dimensions, etc.
- The eigenvalue decomposition of S is given by

 $S = V \Lambda V^{\top}$

where Λ is a diagonal matrix with eigenvalues

 $\lambda_1 > \lambda_2 > \cdots > \lambda_n > 0$

and *V* is a $p \times p$ orthogonal matrix whose columns are the *p* eigenvectors of *S*, i.e. the principal components v_1, \ldots, v_p .

Properties of the Principal Components

- Derived scalar variable (projection to the *j*-th principal component) $Z^{(j)} = v_j^\top X$ has sample variance λ_j , for $j = 1, \ldots, p$
- *S* is a real symmetric matrix, so eigenvectors (principal components) are orthogonal.
- Projections to principal components are **uncorrelated**: $Cov(Z^{(i)}, Z^{(j)}) \approx v_i^{\top} S v_j = \lambda_j v_i^{\top} v_j = 0$, for $i \neq j$.
- The **total sample variance** is given by $\text{Tr}(S) = \sum_{i=1}^{p} S_{ii} = \lambda_1 + \ldots + \lambda_p$, so the **proportion of total variance explained** by the j^{th} PC is $\frac{\lambda_j}{\lambda_1+\lambda_2+...+\lambda_p}$

R code

This is what we have had before:

```
> library(MASS)
> varnames<-c('FL','RW','CL','CW','BD')
> Crabs <- crabs[,varnames]
```
Now perform PCA with function princomp. (Alternatively, solve for the PCs yourself using e_i and e_i svd)

```
> Crabs.pca <- princomp(Crabs)
```
Exploring PCA output

```
> Crabs.pca <- princomp(Crabs)
> summary(Crabs.pca)
Importance of components:
                         Comp.1 Comp.2 Comp.3 Comp.4 Comp.5
Standard deviation 11.8322521 1.135936870 0.997631086 0.3669098284 0.2784325016
Proportion of Variance 0.9824718 0.009055108 0.006984337 0.0009447218 0.0005440328
Cumulative Proportion 0.9824718 0.991526908 0.998511245 0.9994559672 1.0000000000
> loadings(Crabs.pca)
Loadings:
  Comp.1 Comp.2 Comp.3 Comp.4 Comp.5
FL -0.289 -0.323 0.507 0.734 0.125
RW -0.197 -0.865 -0.414 -0.148 -0.141
CI_1 -0.599 0.198 0.175 -0.144 -0.742
CW -0.662 0.288 -0.491 0.126 0.471
```
BD -0.284 -0.160 0.547 -0.634 0.439

Raw Crabs Data

> pairs(Crabs)

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PCA of Crabs Data

- > Crabs.pca <- princomp(Crabs)
- > pairs(predict(Crabs.pca))

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What did we discover?

Now let us use our label information (species+sex).

```
> Crabs.class <- factor(paste(crabs$sp,crabs$sex,sep=""))
```
> Crabs.class

[1] BM [27] BM BF BF [53] BF [79] BF OM OM OM OM [105] OM [131] OM OF OF OF OF OF OF [157] OF [183] OF Levels: BF BM OF OM

Raw Crabs Data - with labels

> pairs(Crabs,col=unclass(Crabs.class))

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PCA of Crabs Data - with labels

- > Crabs.pca <- princomp(Crabs)
- > pairs(predict(Crabs.pca),col=unclass(Crabs.class))

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PC 2 vs PC 3

- > Z<-predict(Crabs.pca)
- > plot(Comp.3~Comp.2,data=Z,col=unclass(Crabs.class))

PCA on Face Images: Eigenfaces

[Turk and Pentland, CVPR 1995](https://www.cs.ucsb.edu/~mturk/Papers/mturk-CVPR91.pdf)

PCA on European Genetic Variation

[Genes mirror geography within Europe, Nature 2008](http://www.nature.com/nature/journal/v456/n7218/full/nature07331.html)

Comments on the use of PCA

- PCA commonly used to project data *X* onto the first *k* PCs giving the *k*-dimensional view of the data that best preserves **the first two moments**.
- Although PCs are uncorrelated, scatterplots sometimes reveal structures in the data other than linear correlation.
- Emphasis on variance is where the weaknesses of PCA stem from:
	- Assuming large variances are meaningful (high signal-to-noise ratio)
	- The PCs depend heavily on the units measurement. Where the data matrix contains measurements of vastly differing orders of magnitude, the PC will be greatly biased in the direction of larger measurement. In these cases, it is recommended to calculate PCs from $Corr(X)$ instead of $Cov(X)$ (cor=True in the call of princomp).
	- Lack of robustness to outliers: variance is affected by outliers and so are PCs.

PCA: summary

PCA

Find an orthogonal basis $\{v_1, v_2, \ldots, v_p\}$ for the data space such that:

- The first principal component (PC) v_1 is the **direction of greatest variance** of data.
- The *j*-th PC *v^j* is the **direction orthogonal to** *v*1, *v*2, . . . , *vj*−¹ **of greatest variance**, for $j = 2, \ldots, p$.

Eigendecomposition of the sample covariance matrix $S = \frac{1}{n-1} \sum_{i=1}^{n} x_i x_i^{\top}$. $S = V \Lambda V^{\top}$.

- \bullet Λ is a diagonal matrix with eigenvalues (variances along each principal component) $\lambda_1 > \lambda_2 > \cdots > \lambda_n > 0$
- *V* is a $p \times p$ orthogonal matrix whose columns are the p eigenvectors of *S*, i.e. the principal components v_1, \ldots, v_p
- Dimensionality reduction by projecting $x_i \in \mathbb{R}^p$ onto first *k* principal components:

$$
z_i = \left[v_1^\top x_i, \dots, v_k^\top x_i \right]^\top \in \mathbb{R}^k.
$$

Eigendecomposition and PCA

$$
S = \frac{1}{n-1} \sum_{i=1}^{n} x_i x_i^{\top} = \frac{1}{n-1} \mathbf{X}^{\top} \mathbf{X}.
$$

• *S* is a **real and symmetric** matrix, so there exist *p* eigenvectors v_1, \ldots, v_p that are pairwise orthogonal and *p* associated eigenvalues $\lambda_1, \ldots, \lambda_n$ which satisfy the eigenvalue equation $S{\nu_i} = \lambda_i{\nu_i}.$ In particular, V is an orthogonal matrix:

$$
VV^{\top} = V^{\top}V = I_p.
$$

S is a **positive-semidefinite** matrix, so the eigenvalues are non-negative:

 $\lambda_i \geq 0$, $\forall i$.

Why is *S* symmetric? Why is *S* positive-semidefinite? Reminder: A symmetric $p \times p$ matrix *R* is said to be positive-semidefinite if

 $\forall a \in \mathbb{R}^p, a^{\top} Ra \geq 0.$

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Singular Value Decomposition (SVD)

SVD

Any real-valued $n \times p$ matrix **X** can be written as $X = UDV^{\top}$ where

- *U* is an $n \times n$ orthogonal matrix: $UU^{\top} = U^{\top}U = I_n$
- *D* is a $n \times p$ matrix with decreasing **non-negative** elements on the diagonal (the singular values) and zero off-diagonal elements.
- *V* is a $p \times p$ orthogonal matrix: $VV^{\top} = V^{\top}V = I_p$
- SVD **always** exists, even for non-square matrices.
- Fast and numerically stable algorithms for SVD are available in most packages.The relevant R command is svd.

SVD and PCA

- Let $X = UDV^{\top}$ be the SVD of the $n \times p$ data matrix X.
- Note that

 $(n-1)S = \mathbf{X}^\top \mathbf{X} = (UDV^\top)^\top (UDV^\top) = VD^\top U^\top UDV^\top = VD^\top DV^\top,$

using orthogonality $(U^\top U = I_n)$ of U .

- The eigenvalues of *S* are thus the diagonal entries of $\Lambda = \frac{1}{n-1}D^\top D$.
- We also have

 $\mathbf{X} \mathbf{X}^\top = (U D V^\top) (U D V^\top)^\top = U D V^\top V D^\top U^\top = U D D^\top U^\top,$

using orthogonality $(V^{\top}V = I_p)$ of *V*.

Gram matrix

 $\mathbf{B} = \mathbf{X} \mathbf{X}^{\top}, \, \mathbf{B}_{ij} = x_i^{\top} x_j$ is called the Gram matrix of dataset $\mathbf{X}.$ **B** and $(n-1)S = \mathbf{X}^\top \mathbf{X}$ have the same nonzero eigenvalues, equal to the non-zero squared singular values of X.

PCA projections from Gram matrix

If we consider projections to **all principal components**, the transformed data matrix is

$$
\mathbf{Z} = \mathbf{X}V = UDV^{\top}V = UD,
$$
\n(1)

If $p \leq n$ this means

$$
z_i = [U_{i1}D_{11},\ldots,U_{ip}D_{pp}]^\top , \qquad (2)
$$

and if *p* > *n* only the first *n* projections are defined (sample covariance will have rank at most *n*):

$$
z_i = [U_{i1}D_{11}, \ldots, U_{in}D_{nn}, 0, \ldots, 0]^{\top}.
$$
 (3)

Thus, **Z** can be obtained from the eigendecomposition of Gram matrix **B**. When $p \gg n$, eigendecomposition of **B** requires much less computation, $O(n^3)$, than the eigendecomposition of the covariance matrix, $O(p^3)$, so is the preferred method for PCA in that case.

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Biplots

> biplot(Crabs.pca,scale=1)

- \bullet PCA plots show the data items (rows of X) in the space spanned by PCs.
- **Biplots** allow us to visualize the **original variables** $X^{(1)}, \ldots, X^{(p)}$ (corresponding to columns of X) in the same plot.

Biplots

Recall that $X = [X^{(1)}, \ldots, X^{(p)}]^\top$ and $\mathbf{X} = UDV^\top$ is the SVD of the data matrix. The "full" PC projection of x_i is the *i*-th row of UD (assuming $p \leq n$):

$$
z_i = V^{\top} x_i = [U_{i1} D_{11}, \dots, U_{ip} D_{pp}]^{\top},
$$
 equivalently: $\mathbf{X} V = U D$.

The *j*-th unit vector $e_j \in \mathbb{R}^p$ points in the direction of the original variable $X^{(j)}$. Its PC projection ν_j is:

 $\nu_j = V^\top \mathbf{e}_j = [V_{j1}, \ldots, V_{jp}]^\top$ (the *j*-th row of *V*)

- The projection of \mathbf{e}_j indicates the weighting each PC gives to the original variable $X^{(j)}$.
- Dot products between these projections give entries of the data matrix:

$$
x_{ij} = \sum_{\ell=1}^{\min\{n,p\}} U_{i\ell} D_{\ell\ell} V_{j\ell} = z_i^\top \nu_j.
$$

Biplots focus on the first two PCs and the quality depends on the **proportion of variance explained** by the first two PCs.

Iris Data

50 samples from each of the 3 species of iris: setosa, versicolor, and virginica

Each measuring the length and widths of both sepal and petals

Collected by E. Anderson (1935) and analysed by R.A. Fisher (1936)

Iris Data

Iris data biplot

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Biplots

• There are other projections we can consider for biplots (assuming $p \le n$):

$$
x_{ij} = \sum_{\ell=1}^p U_{i\ell} D_{\ell\ell} V_{j\ell} = \tilde{z}_i^\top \tilde{\nu}_j
$$

where for some $\alpha \in [0, 1]$:

$$
\tilde{z}_i = \begin{bmatrix} U_{i1}D_{11}^{1-\alpha}, \dots, U_{ip}D_{pp}^{1-\alpha} \end{bmatrix}^\top \quad \tilde{\nu}_j = \begin{bmatrix} D_{11}^\alpha V_{j1}, \dots, D_{pp}^\alpha V_{jp} \end{bmatrix}^\top
$$

- In the case $\alpha = 1$, i.e. $\mathbf{Z} = U_{1:n-1:n}$
	- Sample covariance of the projected points is:

$$
\widehat{\mathsf{Cov}}\left(\tilde{Z}\right) = \frac{1}{n-1} U_{1:n,1:p}^{\top} U_{1:n,1:p} = \frac{1}{n-1} I_p.
$$

Derived variables $\tilde{Z}^{(1)}, \ldots, \tilde{Z}^{(k)}$ are uncorrelated and have equal variance.

Sample covariance between $X^{(i)}$ and $X^{(j)}$ is:

$$
\widehat{\mathsf{Cov}}({X^{(i)}}, {X^{(j)}}) = \frac{1}{n-1} \left({V}D^\top D {V}^\top\right)_{i,j} = \frac{1}{n-1} \tilde{\nu}_i^\top \tilde{\nu}_j
$$

The angle between the projected variables can be interpreted as the correlation between the original variables.

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Iris Data biplot - scaled

```
> ?biplot
```

```
...
```

```
scale: The variables are scaled by lambda ^ scale and the observations
are scaled by lambda \hat{ } (1-scale) where lambda are the singular values
as computed by princomp. (default=1)
```

```
...
```
> biplot(iris.pca,scale=1)

Crabs Data biplots

> biplot(Crabs.pca,scale=0)

US Arrests Data

This data set contains statistics, in arrests per 100,000 residents for assault, murder, and rape in each of the 50 US states in 1973. Also given is the percent of the population living in urban areas.

```
pairs(USArrests)
usarrests.pca <- princomp(USArrests,cor=T)
plot(usarrests.pca)
```
pairs(predict(usarrests.pca)) biplot(usarrests.pca)

US Arrests Data Pairs Plot

> pairs (USArrests)

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US Arrests Data Biplot

> biplot(usarrests.pca)

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Multidimensional Scaling

Suppose there are *n* points **X** in \mathbb{R}^p , but we are only given the $n \times n$ matrix **D** of inter-point dissimilarities.

Can we reconstruct X?

Multidimensional Scaling

Rigid transformations (translations, rotations and reflections) do not change inter-point distances so cannot recover X exactly. However X can be recovered up to these transformations!

Let $\mathbf{D}_{ij} = \|x_i - x_j\|_2^2$ be the squared Euclidean distance between points x_i and *x^j* .

$$
\mathbf{D}_{ij} = ||x_i - x_j||_2^2
$$

= $(x_i - x_j)^\top (x_i - x_j)$
= $x_i^\top x_i + x_j^\top x_j - 2x_i^\top x_j$

- Let $\mathbf{B} = \mathbf{X} \mathbf{X}^\top$ be the $n \times n$ matrix of dot-products, $\mathbf{B}_{ij} = x_i^\top x_j$. The above shows that **can be computed from** $**B**$ **.**
- Conversely, **B** can be recovered from **D** if we assume $\sum_{i=1}^{n} x_i = 0$ (exercise).

Multidimensional Scaling

- **If we knew X, then SVD gives** $X = UDV^{\top}$ **. As X has rank at most** $r = \min(n, p)$, we have at most *r* non-zero singular values in *D* and we can assume $U \in \mathbb{R}^{n \times r}$, $D \in \mathbb{R}^{r \times r}$ and $V^{\top} \in \mathbb{R}^{r \times p}$.
- \bullet The eigendecomposition of **B** is then:

$$
\mathbf{B} = \mathbf{X} \mathbf{X}^{\top} = U D^2 U^{\top} = U \Lambda U^{\top}.
$$

- \bullet This eigendecomposition can be obtained from **B** without knowledge of **X**!
- Let $\tilde{x}_i^\top = U_i \Lambda^{\frac{1}{2}} \in \mathbb{R}^r.$ If $r < p,$ pad \tilde{x}_i with 0s so that it has length $p.$ Then,

$$
\tilde{x}_i^{\top} \tilde{x}_j = U_i \Lambda U_j^{\top} = \mathbf{B}_{ij} = x_i^{\top} x_j
$$

and we have found a set of vectors with dot-products given by B (and hence distances given by D), as desired.

The vectors \tilde{x}_i differs from x_i only via the orthogonal matrix V^\top (recall that $x_i^\top = U_i D V^\top = \tilde{x}_i^\top V^\top)$ so are equivalent up to rotation and reflections.

US City Flight Distances

We present a table of flying mileages between 10 American cities, distances calculated from our 2-dimensional world. Using **as the starting point, metric** MDS finds a configuration with the same distance matrix.

US City Flight Distances

library(MASS)

us <- read.csv("http://www.stats.ox.ac.uk/~sejdinov/sdmml/data/uscities.csv")

```
## use classical MDS to find lower dimensional views of the data
## recover X in 2 dimensions
```

```
us.classical <- cmdscale(d=us,k=2)
plot(us.classical)
text(us.classical,labels=names(us))
```
US City Flight Distances

Lower-dimensional Reconstructions

In classical MDS derivation, we used all eigenvalues in the eigendecomposition of **to reconstruct**

 $\tilde{x}_i = U_i \Lambda^{\frac{1}{2}}.$

We can use only the largest $k < \min(n, p)$ eigenvalues and eigenvectors in the reconstruction, giving the 'best' *k*-dimensional view of the data.

This is analogous to PCA, where only the largest eigenvalues of $\mathbf{X}^\top \mathbf{X}$ are used, and the smallest ones effectively suppressed.

Indeed, PCA and classical MDS are duals and yield effectively the same result.

Crabs Data

```
library(MASS)
crabs$spsex=paste(crabs$sp,crabs$sex,sep="")
varnames<-c('FL','RW','CL','CW','BD')
Crabs <- crabs[, varnames]
Crabs.class <- factor(crabs$spsex)
crabsmds <- cmdscale(d= dist(Crabs),k=2)
plot(crabsmds, pch=20, cex=2,col=unclass(Crabs.class))
```


M_{DS} 1

Crabs Data

Compare with previous PCA analysis. Classical MDS solution corresponds to the first 2 PCs.

Varieties of MDS

Generally, MDS is a class of dimensionality reduction techniques which represents data points $x_1, \ldots, x_n \in \mathbb{R}^p$ in a lower-dimensional space *z*1, . . . ,*zⁿ* ∈ R *^k* which tries to preserve inter-point (dis)similarities.

- It requires only the matrix **D** of pairwise dissimilarities $\mathbf{D}_{ij} = \rho(x_i, x_j)$ (not necessarily Euclidean distances).
- MDS finds representations $z_1, \ldots, z_n \in \mathbb{R}^k$ such that

$$
||z_i - z_j||_2 \approx \rho(x_i, x_j) = \mathbf{D}_{ij},
$$

and differences in dissimilarities are measured by the appropriate loss $\Delta(\mathbf{D}_{ii}, ||z_i - z_j||_2).$

Goal: Find Z which minimizes the **stress function**

$$
S(\mathbf{Z}) = \sum_{i \neq j} \Delta(\mathbf{D}_{ij}, ||z_i - z_j||_2).
$$

Varieties of MDS

- Choices of (dis)similarities and (**stress**) functions lead to different algorithms.
	- **Classical/Torgerson**: preserves inner products instead **strain function** (cmdscale)

$$
S(\mathbf{Z}) = \sum_{i \neq j} (\mathbf{B}_{ij} - \langle z_i - \overline{z}, z_j - \overline{z} \rangle)^2
$$

Metric Shephard-Kruskal: preserves distances w.r.t. squared stress

$$
S(\mathbf{Z}) = \sum_{i \neq j} (\mathbf{D}_{ij} - ||z_i - z_j||_2)^2
$$

• Sammon: preserves shorter distances more (sammon)

$$
S(\mathbf{Z}) = \sum_{i \neq j} \frac{(\mathbf{D}_{ij} - ||z_i - z_j||_2)^2}{\mathbf{D}_{ij}}
$$

Non-Metric Shephard-Kruskal: ignores actual distance values, only preserves ranks (isoMDS)

$$
S(\mathbf{Z}) = \min_{g \text{ increasing}} \frac{\sum_{i \neq j} (g(\mathbf{D}_{ij}) - ||z_i - z_j||_2)^2}{\sum_{i \neq j} ||z_i - z_j||_2^2}
$$

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Nonlinear Dimensionality Reduction

Two aims of different varieties of MDS:

- To visualize the (dis)similarities among items in a dataset, where these (dis)disimilarities may not have Euclidean geometric interpretations.
- To perform **nonlinear** dimensionality reduction.

Many high-dimensional datasets exhibit low-dimensional structure ("live on a low-dimensional menifold").

curvature and branch separation) and on the

Isomap

Fig. 2. The residual

Isomap is a non-linear dimensional reduction technique based on classical MDS. Differs from other MDSs as it uses estimates of geodesic distances between the data points.

[Tenenbaum et al. \(2000\)](http://isomap.stanford.edu/)

dimensional Euclidean representation, as

Isomap

Isomap

- Calculate Euclidean distances \mathbf{D}_{ij} for $i,j=1,\ldots,n$ between all data points.
- Form a graph G with *n* samples as nodes, and edges between the respective K nearest neighbours (K-Isomap) or between i and j if $\mathbf{D}_{ij} < \epsilon$ $(\epsilon\text{-Isomap}).$ MDS to nonlinear data sets fall into two araph *G* (*20*). (**D**) Handwritten
- For i, j linked by an edge, set $\mathbf{D}_{ij}^G = \mathbf{D}_{ij}$. Otherwise, set \mathbf{D}_{ij}^G to be the shortest-path distance between i and j in G . nked by

Run classical MDS using distances $\mathbf{D}_{ij}^G.$

R function: isomap{vegan}.

Handwritten Characters Input-space distances *dX*(*i*,*j*) were measured by

"2": bottom loop (*x* axis) and top arch (*y* axis).

Faces manifold *M*, based on the distances *dX* (*i*,*j*) between pairs of points *i*,*j* in the input space

are detailed in Table 1. The first step deter-

cause we did not expect a constant dimensionality

Downloaded from

Summary

- Other dimensionality reduction techniques:
	- [t-Distributed Stochastic Neighbor Embedding \(t-SNE\)](http://www.cs.toronto.edu/~hinton/absps/tsne.pdf)
	- **e** [Kernel PCA](http://www.mitpressjournals.org/doi/abs/10.1162/089976698300017467)
	- [Locally Linear Embedding](http://www.cs.nyu.edu/~roweis/lle/)
	- **[Laplacian Eigenmaps](http://www.mitpressjournals.org/doi/abs/10.1162/089976603321780317)**
	- [Maximum Variance Unfolding](http://www.cse.wustl.edu/~kilian/research/manifold/manifold.html)
- Further reading:
	- Bishop 12.1
	- \bullet Hastie et al 14.8-14.9
	- [Manifold learning on scikit-learn](http://scikit-learn.org/stable/modules/manifold.html)