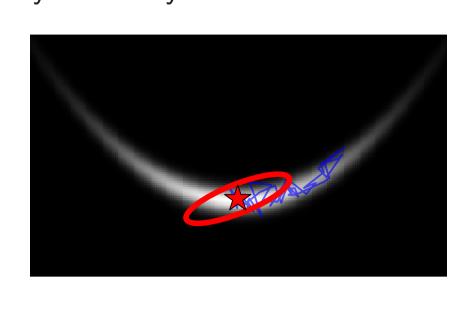
Kernel Adaptive Metropolis-Hastings

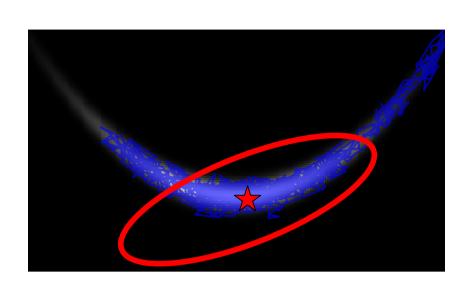
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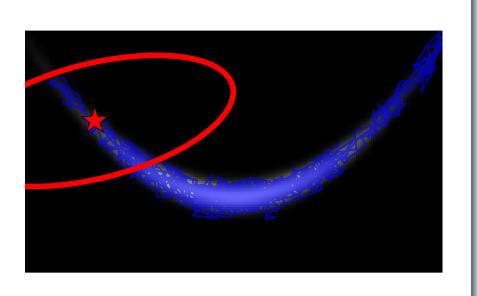
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Adaptive Markov Chain Monte Carlo

- ▶ What proposal and scaling to choose for MCMC?
- ▶ Adaptive MCMC [1]: use history of Markov chain to learn structure of target, e.g. covariance.
- ▶ Only able to learn **global** linear covariance, i.e., scaling in principal directions.
- ▶ May be locally miscalibrated for strongly non-linear targets.

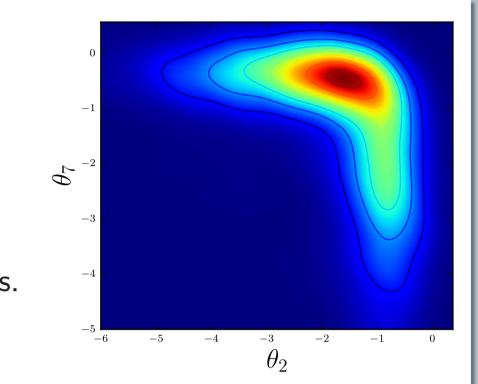






Motivation: Intractable & Non-linear Targets

- ▶ Non-linear targets: Hamiltonian Monte Carlo and MALA work great.
- ▶ However, those depend on gradients and second order information.
- ▶ Sometimes unavailable or expensive, e.g. in Bayesian GP classification, and more generally in Pseudo-Marginal MCMC [2].
- ▶ Right: Sliced posterior over hyperparameters of a GP classifier on UCI Glass.

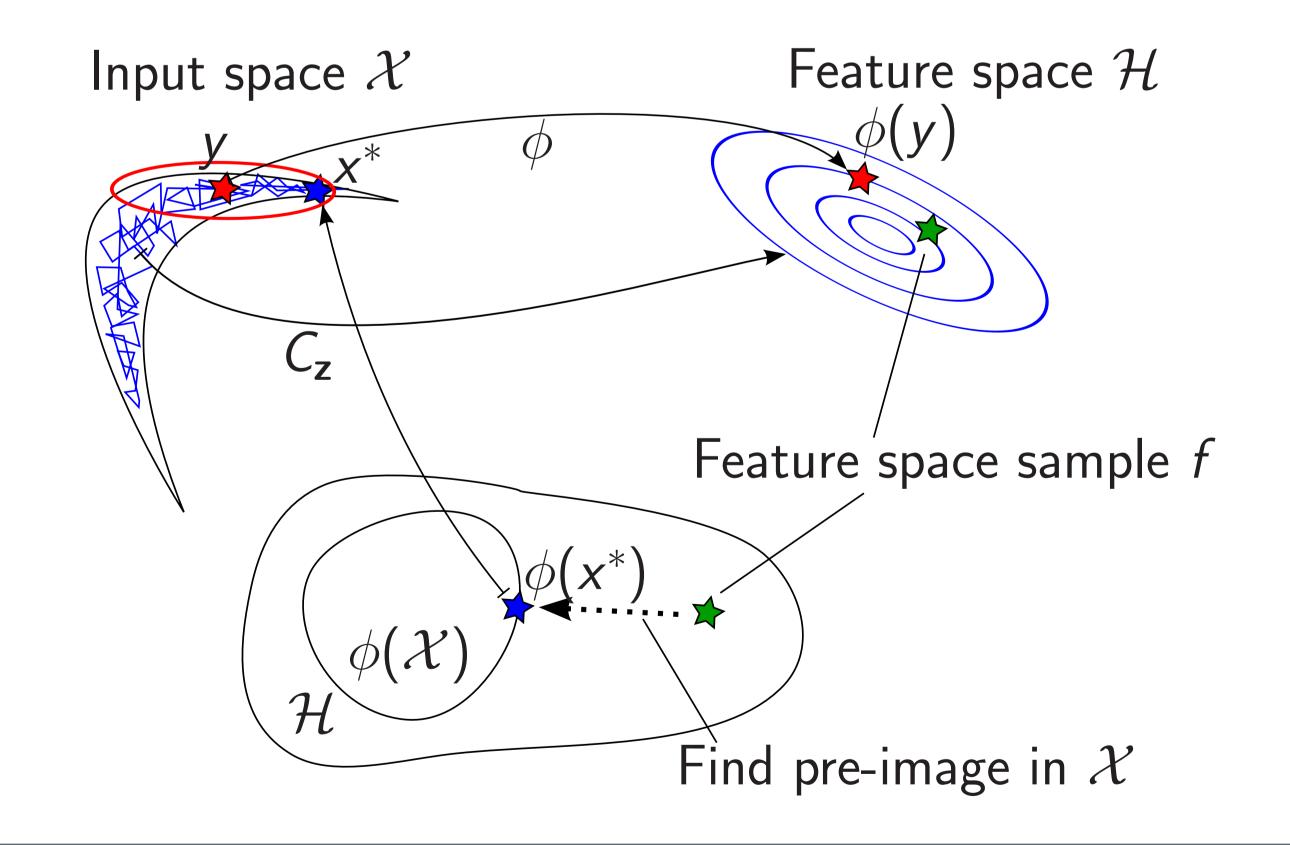


Want adaptive sampler that learns the shape of non-linear targets without higher order information.

Kernel Adaptive Metropolis Hastings – Illustration

Current point: y, a subsample of Markov chain history $\mathbf{z} = \{z_i\}_{i=1}^n$. Goal is an intelligent proposal x^*

- ▶ Capture non-linearities using linear covariance C_z in feature space \mathcal{H} .
- ▶ Sample $f \in \mathcal{H}$ from the Gaussian measure corresponding to $C_{\mathbf{z}}$.
- ▶ Find a point x^* whose feature mapping $\phi(x^*)$ is close to f



Embeddings and Covariance in RKHS

- ▶ For any positive semidefinite function k, there is a unique RKHS \mathcal{H}_k . Can consider $x \mapsto k(\cdot, x)$ as feature map.
- ▶ Embedding of a probability measure: $\mu_P = \int k(\cdot, x) \, dP(x)$ satisfies $\langle f, \mu_P \rangle_{\mathcal{H}_L} = \int f(x) \, dP(x) \quad \forall f \in \mathcal{H}_k$.
- ▶ Covariance operator: $C_P: \mathcal{H}_k \to \mathcal{H}_k$ is given by $C_P = \int k(\cdot, x) \otimes k(\cdot, x) \, dP(x) \mu_P \otimes \mu_P$ [4]
- ► These can be estimated as

$$\mu_{\mathbf{z}} = \frac{1}{n} \sum_{i=1}^{n} k(\cdot, z_i) \qquad C_{\mathbf{z}} = \frac{1}{n} \sum_{i=1}^{n} k(\cdot, z_i) \otimes k(\cdot, z_i) - \mu_{\mathbf{z}} \otimes \mu_{\mathbf{z}}$$

The empirical covariance captures non-linear features of the underlying distribution (c.f. Kernel PCA [6])

Kernel Adaptive Metropolis Hastings – Formal Description

Current point: y, a subsample of Markov chain history $\mathbf{z} = \{z_i\}_{i=1}^n$. Goal is intelligent proposal x^*

1. Sample Gaussian Measure in RKHS: For $eta \sim \mathcal{N}(0,rac{
u^2}{n}I_n)$, the represented RKHS element

$$f = k(\cdot, y) + \sum_{i=1}^{n} \beta_i [k(\cdot, z_i) - \mu_{\mathbf{z}}]$$

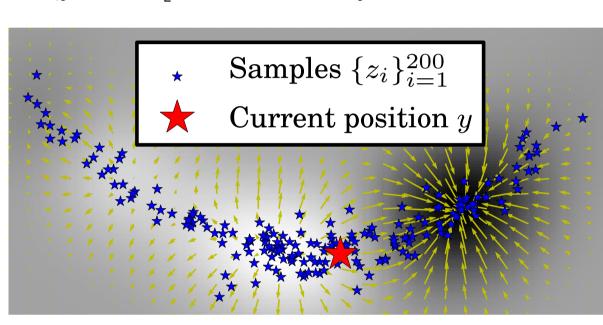
has mean $k(\cdot, y)$ and covariance $\frac{\nu^2}{n}C_z$.

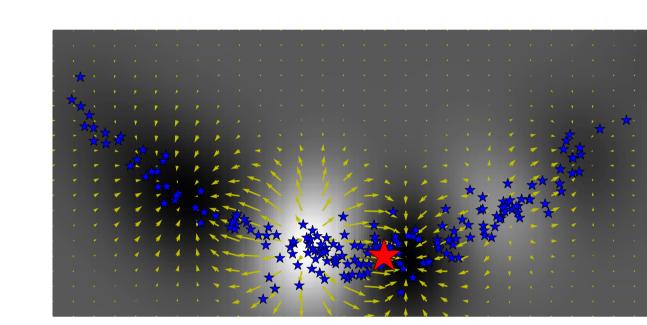
2. Find a point x^* in input space $\mathcal X$ with the feature embedding $\phi(x^*)=k(\cdot,x^*)$ close to f by considering

$$\underset{x \in \mathcal{X}}{\arg\min} \|k\left(\cdot, x\right) - f\|_{\mathcal{H}}^{2} = \underset{x \in \mathcal{X}}{\arg\min} \left\{ \underbrace{k(x, x) - 2k(x, y) - 2\sum_{i=1}^{n} \beta_{i} \left[k(x, z_{i}) - \mu_{\mathbf{z}}(x)\right]}_{=:g(x) \text{ where } g: \mathcal{X} \to \mathbb{R}} \right\}$$

taking a single gradient step w.r.t g, and (optionally) add 'exploration term' $\xi \sim \mathcal{N}(0, \gamma^2)$. This gives $x^*|y,\beta = y - \eta \nabla_x g(x)|_{x=y} + \xi = y - M_{\mathbf{z},y} H\beta + \xi,$

where $M_{\mathbf{z},y} = 2\eta \left[\nabla_X k(x,z_1)|_{x=y}, \dots, \nabla_X k(x,z_n)|_{x=y} \right]$ is based on kernel gradients (readily available).





3. Integrating out RKHS samples and gradient step (i.e., eta and ξ) gives Gaussian proposal on input space.

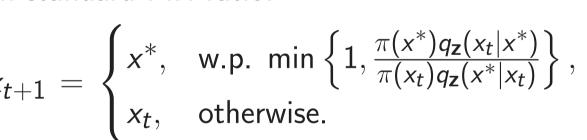
Proposed Algorithm: MCMC Kameleon

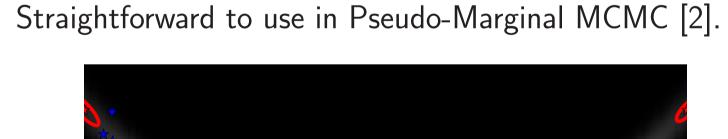
MCMC Kameleon

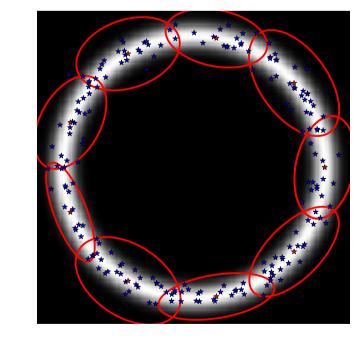
Input: unnormalized target π , subsample size n, scaling parameters ν, γ , kernel k,

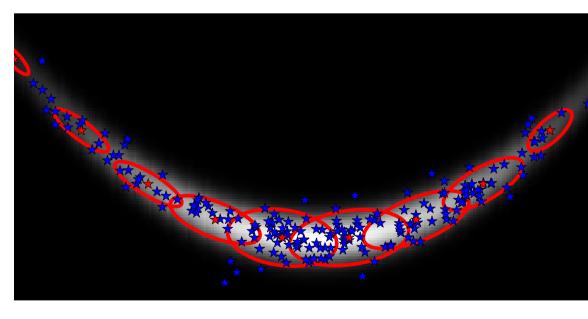
At iteration t+1,

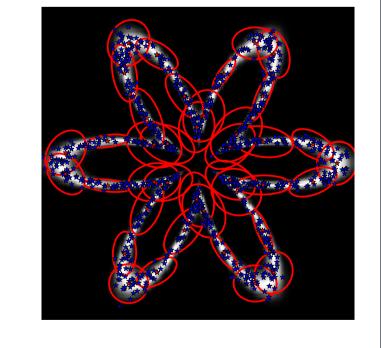
- 1. Obtain a random subsample $\mathbf{z} = \{z_i\}_{i=1}^n$ of the chain history $\{x_i\}_{i=0}^{t-1}$,
- 2. Sample proposed point x^* from $q_z(\cdot|x_t) = \mathcal{N}(x_t, \gamma^2 I + \nu^2 M_{z,x_t} H M_{z,x_t}^\top)$,
- 3. Accept/Reject with standard MH ratio:











Kameleon proposals capture **local** covariance structure!

Examples of Covariance Structure for Standard Kernels

▶ Linear kernel: $k(x, x') = x^{\top}x'$

$$q_{\mathbf{z}}(\cdot|\mathbf{y}) = \mathcal{N}(\mathbf{y}, \gamma^2 \mathbf{I} + 4\nu^2 \mathbf{Z}^{\top} H \mathbf{Z})$$

which results in the classical Adaptive Metropolis of [5].

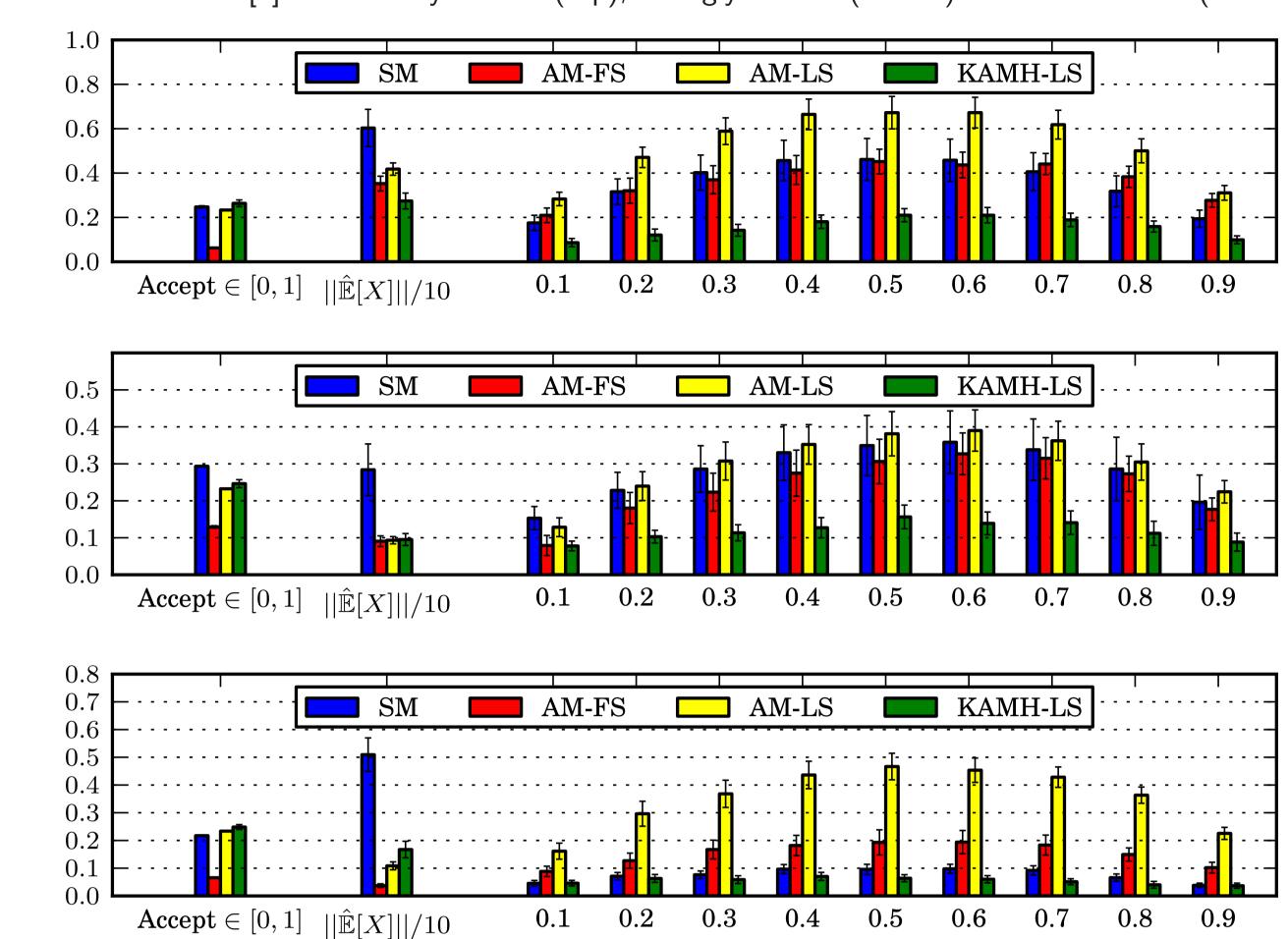
► Gaussian kernel: $k(x, x') = \exp\left(-\frac{1}{2}\sigma^{-2} \|x - x'\|_{2}^{2}\right)$

$$\left[\operatorname{cov}[q_{\mathbf{z}(\cdot|y)}]\right]_{ij} = \gamma^2 \delta_{ij} + \frac{4\nu^2}{\sigma^4} \sum_{a=1}^n \left[k(y, z_a)\right]^2 (z_{a,i} - y_i)(z_{a,j} - y_j) + \mathcal{O}(n^{-1}),$$

where the previous points z_a influence the covariance, weighted by their similarity $k(y, z_a)$ to current point y.

Synthetic examples: Convergence Statistics

8-dim. Banana of [5]: moderately twisted (top), strongly twisted (middle) and 8-dim Flower (bottom).



Reported are acceptance rates and errors for means and quantiles.

Real-life Example: Bayesian Gaussian Process Classification

► Consider a standard GPC model

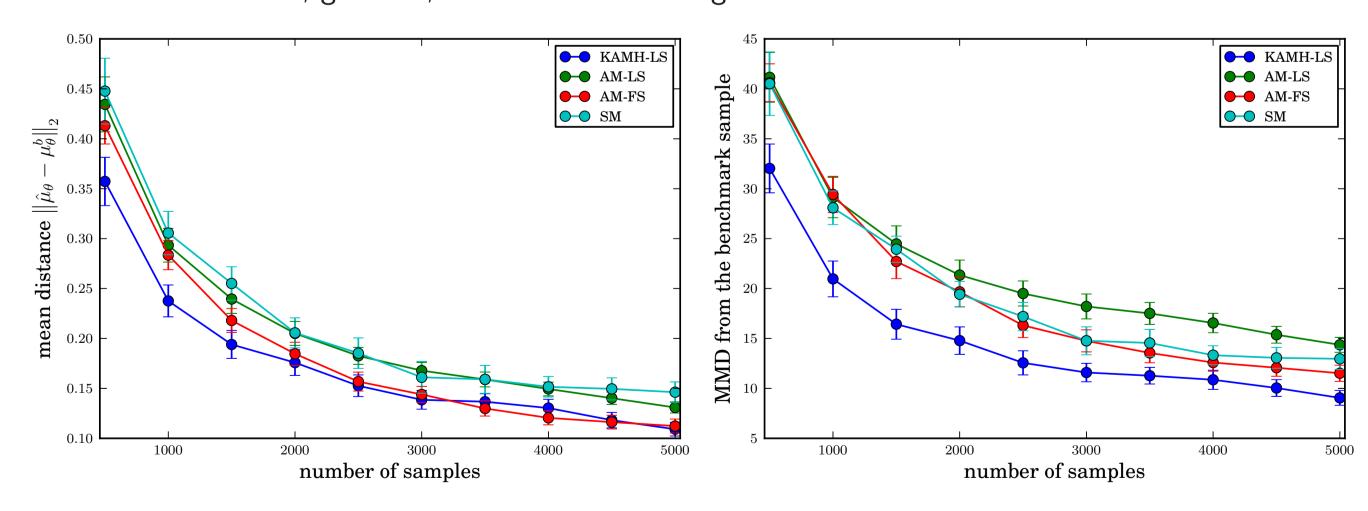
$$p(\mathbf{f}, \mathbf{y}, heta) = p(heta)p(\mathbf{f}| heta)p(\mathbf{y}|\mathbf{f})$$

where $p(\mathbf{f}|\theta)$ is a Gaussian Process with an exponentiated quadratic covariance (ARD: one scale parameter per input space dimension), and $p(\mathbf{y}|\mathbf{f})$ is a sigmoidal function.

- ▶ Recent work [3] focused on Pseudo-Marginal MCMC to sample $p(\theta|y) = p(\theta) \int d\mathbf{f} p(\theta, \mathbf{f}|y) p(\mathbf{f}|\theta)$.
- ▶ Unbiased estimate of $\hat{p}(\mathbf{y}|\theta)$ via importance sampling with $q(\mathbf{f})$ obtained via Expectation Propagation:

$$\hat{p}(heta|\mathbf{y}) \propto p(heta)\hat{p}(\mathbf{y}| heta) pprox p(heta)rac{1}{n_{ ext{imp}}} \sum_{i=1}^{n_{ ext{imp}}} p(\mathbf{y}|\mathbf{f}^{(i)})rac{p(\mathbf{f}^{(i)}| heta)}{q(\mathbf{f}^{(i)})}$$

▶ No access to likelihood, gradient, or Hessian of the target.



Performance on UCI Glass dataset: 8-dimensional non-linear posterior $p(\theta|\mathbf{y})$.

Literature

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